

# 2022 Explorer Class

# LINN-BENTON ROV



The rootin'gst, tootin'gst ROVs in the sea!



**Four Eyes**



**72 x 40 x 30 cm**



**13 kg**



**6,000 USD**

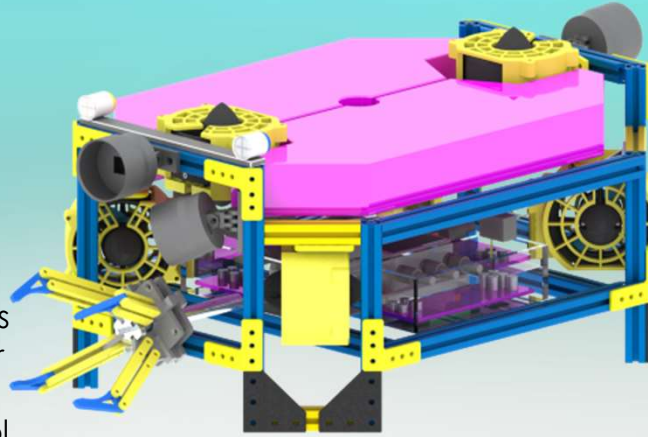


**3000 hours**



## Special Features

- Modular design
- Aluminum frame
- Multiple digital cameras
- Pneumatic manipulator
- Depth sensor
- Laser measurement tool



Linn-Benton Community College

Albany, Oregon, USA

1480 km

## Safety Features

- Waterproof connectors
- Shrouded thrusters
- Fused power converters
- Epoxy-potted circuit boards
- Sharp edges removed
- Master power switch

## Company Information

Linn-Benton ROV has been participating in MATE competitions since 2008. This year's team, comprised of students spanning all four undergraduate years, and from a variety of disciplines, built on the foundations created by past teams to design a sleek, functional, and rootin' tootin' vehicle.

Nolan Andersen <i>Laser Engineer</i>	Phoebe Andromeda <i>Sensors Engineer</i>	Nic Barden <i>Vertical Profiler Engineer</i>	Grant Baysinger <i>Cameras &amp; CV Engineer</i>	Kyle Davis <i>Vertical Profiler Engineer</i>	Levi Kaup <i>Controls Engineer &amp; Pilot</i>
Sara Leathers <i>Frame Engineer</i>	Chloe Madden <i>Controls Engineer &amp; Copilot</i>	Remy Rouyer <i>Cameras &amp; CV Engineer</i>	Quade Stiansen <i>Cameras &amp; CV Engineer</i>	Morgan Sylvia <i>Laser Engineer</i>	Alexander Van Brocklin <i>Laser Engineer</i>
Kelly Watkins <i>Vertical Profiler Engineer</i>	Emilia Watts <i>Vertical Profiler Engineer</i>	Kathy Austin, Ph.D. <i>Writing Advisor</i>	Heather Hill <i>Co-Advisor</i>	Greg Mulder, Ph.D. <i>Lead Advisor</i>	Mark Urista <i>Speech Advisor</i>

