Team Composition:

- Florentinov Sergey - CCO 3 years
- Vysheboev Viktor - programmer for 3 years
- Olga Checchenko - CTO programmer for 8 years
- Sidorinov Sergey - designer of a service station for 3 years

Participating for the first time:

- Nikita Sapsal - programmer (2nd year, oil and gas business) 1 year
- Pochailov Pogatli - designer (MTF, shipbuilding) 1 year
- George Sibyanin - designer (1st year, FEIT TCE) 1 year
- Kirill Kondrashin - designer (1st year, FEIT TCE) 1 year
- Viktor Stadnikov - electronics engineer (1st year, TET) 1 year
- Alexander Vashchenko - electronics engineer (1st year, TET) 1 year
- Yaroslav Rako - electronics engineer (1st year, ESF) 1 year
- Yuri Markin - designer (1st year, FEIT TCE) CMO 1 year

We are located in the Russian Federation,
Primorsky Krai, Vladivostok
The path traveled: 8919 km

Personnel Safety:
To ensure the safety of the team during the development of the device, checklists were developed for safe use of ROV, cable manager, pilot, and others

ROV Safety:
All dangerous components of the device (propellers, electronics units and a device for collecting samples) were marked with special signs prohibiting them from touching when the ROV is activated. Access to the blades of the screws is limited by grilles to avoid the possibility of getting into the blades of anything. All the sharp corners of ROV were worn off. A fuse designed for a current of 30 A is installed on the cable next to the connector.

The total cost of the device: 275 tr.
Length of the device: 620 mm
Width of the unit: 620 mm
Height of the device: 250 mm
Weight of the device: 10 kg
The device, along with the entire payload, has a slightly positive buoyancy, thanks to two isopink blocks installed on top of the main plate.

Features:
cameras providing an optimal field of view both when moving and when working with a manipulator, a long cable (25 meters) and an optimized power supply system, powerful software tools for image stitching.