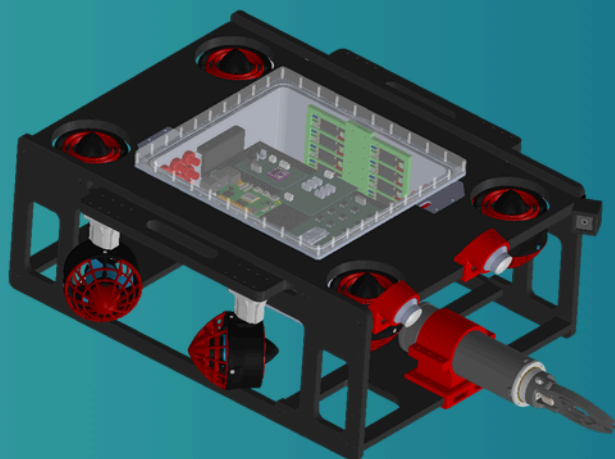




ROV Name: EVA

Designed and built by PoliTOcean

Turin, Italy
6700 km travelled

This is the 8th time we participate in
MATE ROV World Championship
competition!

Design and build time	Project cost	Mass	ROV Dimensions (unarmed)
Over 4,000 hours of work	11,102 \$	18 kg	LxWxH (mm) = 565x498x220

Carlo Stefano Secli	MEng	TL
Samuele Rizza	MEng	MATE PM
Davide Colabella	MEng	MATE CTO
Giorgia Sforza	MEng	R&D PM
Lucrezia Caviasso	MEng	R&D CTO

Vincenzo Segreto	MEng	Hydro HoD
Giuseppe Gentile	MEng	Hydro
Giuseppe Forbice	BSc(Eng)	Hydro
Benicio Fernandez	MEng	Hydro
Alice Reano	MEng	Hydro

Marco Coronelli	MEng	Ctrl HoD
Andrea Gozio	MEng	Ctrl
Seida Dapaj	MEng	Ctrl
Andrea Di Cataldo	MEng	Ctrl
Matteo Gibbin	MEng	Ctrl
Filippo Rosso	MEng	Ctrl
Alesk Demir	MEng	Ctrl
Ahmet Mete Ucar	BCs(Eng)	Ctrl

Filippo Benevenga	MEng	S/FW
Marialuigia Brizzi	MEng	S/FW
Andrea D'Ambrosio	BSc(Eng)	S/FW

Alessandro Morra	BSc(Eng)	Mech HoD
Vincenzo Gentile	MEng	Mech
Michela Aru	MEng	Mech
Alberto Giordano	BCs(Eng)	Mech
Marco Leone	BCs(Eng)	Mech
Su Kalkan	BCs(Eng)	Mech
Emre Sarikaya	BCs(Eng)	Mech
Mostafa Akhdar	BCs(Eng)	Mech
Roje Dio Gonzales	BCs(Eng)	Mech

Rosario Gianni	BSc(Eng)	Eln HoD
Marco Sbardella	MEng	Eln ToD
Samuele Moscatelli	MEng	Eln
Dario Balsells	BCs(Eng)	Eln
Giorgio Piovano	BCs(Eng)	Eln
Antonio Riscica	BCs(Eng)	Eln
Edgardo De Angelis	BCs(Eng)	Eln
Pietro Canta	MEng	Eln
Dawit Pinto	BCs(Eng)	Eln
Rossella Affatato	BCs(Eng)	Eln
Andrea Ballarati	PhD	Eln



Safety features

- Shrouded thrusters
- Status LED
- Over current and over voltage protection

Special features

- Heave, pitch and roll control
- Stereo and 360° vision
- Electrical Manipulator
- Removable Tether