

UWROV NanoFloat Design & Safety Compliance

UWROV's 2024 profiling float, the *NanoFloat* 1.0, is unprecedented in its innovative design, specially optimized for the 2024 MATE RFP.

NanoFloat is designed around two primary objectives: fast profiling for **Task 4: Vertical Profiling**, and remote pressure data transmission for **Task 4: Data Visualization**. To excel at these primary objectives, *NanoFloat* is built with reliability, and operational simplicity, and cost-effectiveness as its core design principles.

We prioritized *NanoFloat*'s **Task 4** performance by maximizing buoyancy differential and wireless performance, while maintaining sufficient mission duration, processing power, and sensor accuracy.

The buoyancy drive uses a custom linear actuator to extend the bottom endcap, with a brushed DC motor-driven screw serving as the actuator. The central ESP32 microcontroller communicates with the pressure sensor and uses its data to inform motor actuation. When the float surfaces, the ESP32 generates a WiFi network to which the surface station connects for wireless communication and visualization of the logged data.

SMA wifi antenna
range tested to 30m

Pressure sensor
rated to 100m depth

O-rings for sealing

ESP32C3 microcontroller
for onboard computation,
wifi network

2A Littelfuse inline with
battery pack based on fuse
calculations found in SID

Wiring channels
built into 3D prints

6v battery pack with
3D printed housing

Limit switch to detect
when float is open to
prevent flooding

Brushed DC motor in
custom buoyancy engine

3D printed piston
buoyancy mechanism

Ballast attachment
point to tune buoyancy

150mm overall length for ultra portable, cheap, scalable design

Safety Requirements Verification:

- ✓ ELEC-NRD-001: *NanoFloat* runs on a **6V DC** nominal **internal** battery pack with a **2A** fuse, which is **under** the 12V DC and 6A requirement.
- ✓ ELEC-NRD-002: *NanoFloat* does **not** contain prohibited devices (no cameras, no thrusters). *NanoFloat* **does use** a variable buoyancy drive that enables motion in the water column.
- ✓ ELEC-NRD-004: *NanoFloat*'s battery pack consists of **4 non-rechargeable (primary) alkaline AAA batteries**. Batteries are securely mounted in a custom 3D-printed **housing structure**.
- ✓ ELEC-NRD-005: *NanoFloat* uses a **2A Micro Blade Littelfuse** inline with its battery pack. The fuse is located **0.3cm away** from the battery pack, with a **1.2cm wire** connecting it to the positive terminal, which is **less than 5cm requirement**. It can be **easily inspected** by removing the internal electronics carriage from the housing.
- ✓ ELEC-NRD-006: *NanoFloat*'s design meets the requirement that the enclosure opens if internal pressure exceeds external. *NanoFloat*'s end cap, which is **2.6cm in diameter and exceeds the 2.5cm minimum diameter**, serves as a pressure relief plug.
- ✓ ELEC-NRD-007: The *NanoFloat* SID can be found in the SID section of the technical documentation.