Sleepy Fishy by the Water Jets

ROV SPECS



Special Features:

Sleepy Fishy is designed to perform tasks to further scientific research and ocean conservation efforts:

- 3D printed vectored frame is both lightweight but waterproof
- Pneumatic claw transports and positions objects with precision
- Dual camera setup enables high quality video capture for photogrammetry and CAD design

Safety Features:

- Control board equipped with fuses to protect from overload
- Strain relief system to prevent cable stress
- Thrusters have IP-20 standard 3D printed shrouds/guards
- Pneumatic system has shut off valve and regulator
- No sharp edges or protrusions on ROV frame could lead to potential injury during handling

COMPANY SPECS



Company Member	Role(s)
Amaan Shaghel	CEO, Pilot
Kaylee Hou	COO, Electrical Lead
Akili Ploudre	Mechanical/Design Lead
Zach Joseph	Photogrammetry Lead, Co-Pilot
Joseph Rodriguez	Tools Lead, Electrical Team
Zayn Ashraf	Mechanical Team
Nina Sediki	Mechanical Team
Nadjila Sediki	Mechanical Team
Sebastian Morris	Electrical Team
Kshitij Pete	Mechanical Team
Antonio Pantaleon	Electrical Team
Aditi Verma	Brand Designer
Gina Bochicchio	Mentor

MATE Competition History: First year competing

Distance Traveled: 3647 km College Levels Represented:

First-Year to Third-Year students

SAN DIEGO MIRAMAR COLLEGE, CA, USA