

Company: SFROBOTICS (9th Year) Team Name: Mariner Mayhem

City: St. Francis, WI Home Country: USA

JSA TABLE:

Task	Hazards	Controls	Resonsible Person(s)	Initial(s)
Entering/	Slipping	All Members are required to have either a cap or hair tied back and wear closed-toed shoes while on deck to avoid personal injury.	Desiree Halsey, CFO	
Exiting the Pool Deck	Damaging Equipment	SFROBOTICS Members ensure careful transportation of equipment to avoid possible equipment damage and environmental damage.	Andre Moreno, Software Lead	
Deck Operations	Miscommunication	To avoid miscommunications prior to set up, SFROBOTICS has devised a deck set-up checklist (pg. 2) and flow chart (pg. 3) to effectively move through deck set-up.	Andre Moreno, Software Lead	
Setup	Personal Injury	SFROBOTICS practices deck set-up and all members are trained on safely hauling heavier equipment to prevent personal injury	Emmitt Esselstrom, CEO	
Power Up	Excess Current to ROV Systems	Emmitt Esselstrom CEO		







JSA TABLE:

Task	Hazards	Controls	Responsible Person(s)	Initial(s)	
Poolside Operations	Personal Injury	All SFROBOTICS members have undergone through proper deck operations procedures as well as wearing proper safety gear, such as safety glasses, to prevent personal injury while handling ROV equipment.	Desiree Halsey, CFO		
Deck Operations Breakdown	Mishandling Equipment	SFROBOTICS members ensure proper handling of equipment postsession to prevent damage to the ROV equipment.	Andre Moreno, Software Lead		
Training		All SFROBOTICS team members are required to participate in Safety Training that consists of a review of SFROBOTICS safety practices in addition to a review of safety in SFROBTOICS ROV Operations.			
Required Personal Protection Equipment (PPE)		All SFROBOTICS team members are required to wear safety glasses whenever interacting with the ROV on the pool deck. Team members are required to wear safety glasses while operating the ROV.			

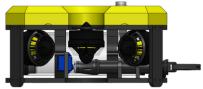
Deck Operations Checklist

Deck Operations Checklist: Created by Andre Moreno and reviewed by Desiree Halsey, and Emmitt Esselstrom. Document updated May 2024.

Task Group	Individual Tasks			
Pre-Power Up	 Area is clear and safe All members are wearing appropriate attire and safety wear Verify all power prior to prep is off Verify tether is secure, knot-free, and free of damage Power source is correctly connected to topside enclosure Verify all electronics are securly connected and damage-free ROV is free form obstrucitons 			
Verify topside enclosure is receiving 12V Surface laptop is powered on and running ROV software Announcer calls out "ROV is powered!" Power on topside enclosure Announcer calls out "Preforming pre-launch tests!" Test all ROV systems(thrusters, lights, claw, cameras)				
ROV Launch	 Members on pool call out "Launching!" ROV is carefully placed into water ROV is checked for bubbles, leaks, failed systems. If no issues persist, announcer calls out "Flying Out!" 			
ROV Retrieval	 Annoucer calls out, "ROV surfacing" Pool side members call out, "ROV Surface, disable systems" Annouceer calls out, "Systems disabled" Pool side member carefully removes ROV from water Post-removal, pool side member calls out, "ROV on deck" Pilot powers down all system. Team begins area break down 			
Leak Detections	 Power down all systems (ROV and topside enclosure) Remove ROV from water Inspect ROV for leak and locate source of leak Use soapy water and pressure tools to verify source Check systems for any liqud damage or assess potential hazards Document occurance and create plan to change design 			
Loss of Communication	 Annoucer calls out, "ROV DC" Power Cycle PSU and reboot systems If communication restores, verify system integrity and resume mission If LoS presists, retireve ROV via tether if LoS persists, being to troubleshoot possible sources of LoS Document LoS occurance and create plan to resolve issue. 			
Pit Maintenance	 Pit is organized, clean, and free of unecessary obstructions All equipment and cables are safely stored and create no hazard Verify electrical cords/outlets to not present possible hazard Inventory supplies and create list(s) of potential items needed upon disaster Verify ROV and all systems are clean and safely stored preventing hazard or possible damage ROV is ready available to go for next run 			







Deck S	etup	Flow	Chart
--------	------	-------------	-------

		Power Up/		
Unloading	ROV Set Up	Communication	Testing	ROV Launch
		Setup		

Emmitt Esselstrom (Pilot/ Operations)



Verify table is clear and ready to be loaded with materials Plug topside enclosure into PSU and connect USB and CAT cable into laptop

Turn on PSU

Ensure ROV receives joystick input, claw and camera tilt is funcitonal

Confirm systems(thrusters, claw) are functional upon submersion

Andre Moreno (Co-Pilot/ Announcer)



Grab surface laptop, monitor and peripherals.

Plug monitor into laptop and lay out plans Verify ROV is receving communication (network and cameras)

Ensure all cameras are receiving proper communication Verify camera systems are functional upon submersion

Desiree Halsey (Tether/ Props)



Go to pool side with ROV and tether Ensure tether is tangle free and ready to be fully extended

Postion tools needed for missions for quick access Double check tether and ROV for any potential hazards

Lower ROV into water

Brady Thorne (Operations)



Unload ROV, push cart aside Verify all connecitons are secure and do not present a hazard

N/A

Double check all connections surface-level are secure

Keep Time

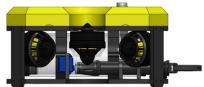
Cole Cushing (Back Up)



Deck Setup Flow Chart: Created by Andre Moreno and reviewed by Desiree Halsey, and Emmitt Esselstrom. Document updated May 2024.







Company: SFROBOTICS (9th Year) Team Name: Mariner Mayhem

City: St. Francis, WI Home Country: USA

Training Log:

Team Member	Safety Training	ROV Operations Training
Emmitt Esselstrom Role(s):		
Andre Moreno Role(s):		
Desiree Halsey Role(s):		
Brady Thorne Role(s):		
Cole Cushing Role: Back Up (if available)		