Meet The Underwater Research Robotics Team

<table>
<thead>
<tr>
<th>Name</th>
<th>Grade</th>
<th>Company Title</th>
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<tbody>
<tr>
<td>Nikolas Jones</td>
<td>12</td>
<td>Pilot &amp; Software Technician</td>
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<tr>
<td>Clayton Thomson</td>
<td>12</td>
<td>Pilot &amp; Engineer</td>
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<tr>
<td>Sarah Rabbideau</td>
<td>10</td>
<td>Safety Officer</td>
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<tr>
<td>Lydia Thomson</td>
<td>9</td>
<td>CEO</td>
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<tr>
<td>Gus Wirgau</td>
<td>9</td>
<td>Lead Technician &amp; Pilot</td>
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<tr>
<td>Lucas Thomson</td>
<td>9</td>
<td>Project Specialist &amp; Tether Handler</td>
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<tr>
<td>Gunner Moe</td>
<td>9</td>
<td>Engineer &amp; Designer</td>
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<tr>
<td>Elizabeth Rabbideau</td>
<td>8</td>
<td>Financial Officer &amp; Tether Handler</td>
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<tr>
<td>Abbey Glover</td>
<td>8</td>
<td>Chief Financial Officer</td>
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**Special Sensors**
- Leak Sensors
- Depth Sensor
- ROV Safety Kill Switch
- Remote Temperature Sensor

**Special Features**
- 15 Meter Tether
- Mechanical Gripper
- HD Color Camera
- Micro-ROV
- No lasers or fluid power

**ROV Specs:**
9.5 Kilograms
Frame is made of ABS
42 cm in diameter
25 amp in-line fuse
Valued at $3,753
Total build hours = 120

Travel distance to the Great Lakes Regional Competitions is 1,400 miles.

Our team has finished in first place at the Great Lakes Regional eight times and we have had five...