

Arab Academy For Science, Technology And Maritime Transport

Spec. Sheet 2011 Mate R.O.V Competition





Team Specs

Home country: Alexandria, Egypt

Team name: A.A.S.T Team

Distance travelled: From Cairo, EG to Houston, US about 11279.38

Km, 7008.87 Miles

Participation Times: It's our 1st time to join the MATE ROV

Competition.

Team Members: (* before name means people who are going to

make it to NASA)

| NAME | Major | NAME | Major |
|-------------------------|--------------------|-----------------|------------------------|
| *Abdulrahman Abul−khair | Mechanical | Ahmed Elgbaly | Mechanical Engineering |
| | Engineering | | |
| *Ahmed Ramy | Marine Engineering | Mahmoud Farahat | Mechanical Engineering |
| *Ahmed Zaghloul | Mechanical | Mohamed Abul- | Marine Engineering |
| | Engineering | Maati | |
| *Karim Gamal | Electronics | Mohamed El- | Mechanical Engineering |
| | | Banna | |
| *Mohamed Gaber | Mechanical | Mostafa El- | Marine Engineering |
| | Engineering | Missery | |
| *Mohammed EL-Halwagy | Electronics | Osama El-Sayed | Electrical Engineering |
| *Mohannad Osman | Mechanical | Ziad Saaed | Electrical Engineering |
| | Engineering | | |
| *Sayed Abdel-Halim | Marine Engineering | Abdelrhman | Mechanical Engineering |
| | | Barghash | |

R.O.V Specs

General description

ROV name: Tahrir.

Cost: about 2,000 \$.

Weight in air: about 10 Kg

Dimensions: Approximately L×W×H 65×35×25 cm.

Material used: PVC tubes, and Artilon Plastic for arm.

Vehicle Description

Thrusters: 6Axial / Lateral converted bilge pumps

2Vertical converted bilge pumps.

Manipulators: 2 functions artilon arm.

Sensors: "Garmin Fish Finder 140" for depth measurement.

Safety features: kort nozzle, isolation by optocoupler, heat sink

Special features: sonar, game pad interface, heavy duty artilon arm, converted bilge pumps, totally self designed manufactured arm.

