ROV - Chimera

ROV Competition History

- 4th Year Ross
- 3rd Year Alex, Lendz
- 2nd Year Chris, Lisa
- 1st Year Rachel, Thomas, Kage

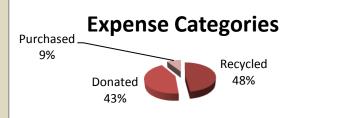
Distance to Competition

• 3,058 Km



ROV SPECS

Almost 50% of this ROV came from recycled parts. The final cost of Chimera was approximately \$1,000. \$850 of this \$1,000 was donated; leaving only \$150 in out-ofpocket expenses. Chimera's frame was created with 1/2" PVC (Polyvinyl Chloride) Pipe. The frame is 96cm x 43cm x 46cm and weighs 17.9 kgs in air. Specially cut PVC Boards connected by steel rods created a protective frame that integrated two Rule 3700 bilge pumps. Two Rule 1100 bilge pumps were added for precision turning and underwater visibility was created using four modified Anaconda Cameras. Also incorporated are two payload tools: an oil capping system and sample collecting vacuum. The control system was programmed in RoboRealm and runs using a Linx Motion Servo Board. Chimera has an onboard electronics system that is inside a PVC Housing connected to the surface using a custom-built tether. The topside electronics consist of a joystick and control unit. A major innovation this year was the internal cooling system for our underwater electronics and our automatic shutoff system.





Thomas – Design Eng – Studying Marine Science

Ross – Pilot – Studying Marine Science

Lisa – CIO – Studying Mathematics

Chris – CEO – Studying Aeronautical

Engineering

Kage – Computer Tech – Studying Computer Programming

Alex – Ops Mgr – Studying Oceanography Lendz – Tech Spt – Studying Everything Rachel – CFO - Studying Marine Biology



NOTABLE SAFETY FEATURES – KILL SWITCH, MULTIPLE FUSES, MOTOR PROP COVERS