

Company Statistics

Company Name: Eastern Edge Robotics, Memorial University of Newfoundland

Home Province: Newfoundland and Labrador, Canada

Distance Traveled: 2363 km, to Alpena, Michigan

Competition Participation: 12th Year Participating in the MATE ROV Competition

Education Level: Post-Secondary, Ranging from freshman to senior students



Employees

Mechanical Engineering

Nathan Ash	CTO, Mechanical
Jeremy Coleman	Tool Development
William Dominie	Camera Developer
Stephen Fudge	Tool Development
William Glatt	Tool Development
Calvin Gregory	CTO, Strutral
Himanshu Ragtah	Chassis Developer
Thom Smith	CTO, Fabrication
Connor Whalen	Tool Development
William Whelan	Tool Development
Stephen Whiffen	Tool Development

Positions

Electrical & Computer Engineering

Lauren Hayes
Scott Henderson
Michelle Mifflin
Tim Oram
Jacob Parsons
Bethany Randell
Jacob Rodgers
Craig Ryan
Michael Schwinghamer
Thomas Seary
Whymarrh Whitby

Positions

Software Developer
Electrical Engineer
Electrical Engineer
CTO, Software
Software Developer
CTO, Electrical
Electrical Engineer
Software Developer
Electrical Engineer
Software Engineer
Software Developer

Admin

Coralie Brown
Kyle Doody
Verity Furlong
Christina Hamlyn
Petros Mathioudakis
Erin Mathews
Calvert Pratt
Kaitlin Quinlan

Positions

Chief Marketing Officer
CEO
Safety Officer
Graphic Artist
Pilot
Public Relations Officer
CFO
COO

ROV KETO

ROV Stats:

ROV Name: KETO
 ROV Total Cost: \$32,245.00
 Primary Material: Lexan
 Dimensions: 69.3(L) x 32.5cm(H) x 36.8cm(W)
 Weight: 28kg

Safety Features:

- Pre-Dive Checklist incorporated into control software
- All motors contained within chassis
- Circuit Breaker installed in topsides control
- Software kill-switch which disables all moving components
- Safety Warnings on all moving components

Special Features:

- Redesigned for high maneuverability
- ROV fore and aft are software-interchangeable
- Redesigned for increased structural strength
- Modular ROV Design
- Multi-Directional Camera Systems
- Capable of High Resolution Video Streaming

