





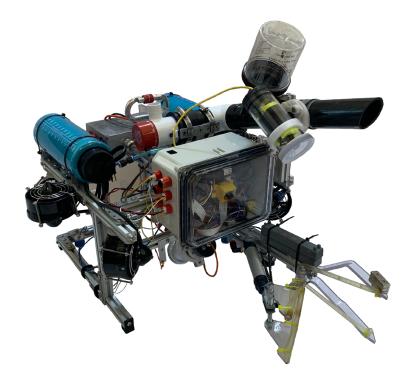
## MODULAR FRAME & BUOYANCY

Adjustable Buoyancy and beam frame for easy configuration and adaptation



DETACHABLE Mini ROV

Detachable Sample Collector "Axolotl" to reach small spaces



# **SPEC SHEET 2021**



#### ROS ARCHITECTURE

Modular Reliable Robot Operating System



# DIGITAL CAMERA SYSTEM

High quality low latency video feed keeps operaters updated and aware

## **SAFETY FEATURES**



#### **ADVANCED TCU**

Access Voltage, ROV Status, and Other Data Easily and Safely



### **SHEATHED TETHER**

Protects the ROV Power, Pneumatics, and Communications Lines



#### ONE CLICK ON AND OFF

Ensure Deck Crew Safety With Easy Shutdown of ROV

## **FACTS & FIGURES**

#### **DIMENSIONS**

Length	50 cm
Width	60 cm
Height	37 cm

**WEIGHT**.....18.5 kg

**TOTAL COST.....**\$4,465.66

DESIGN & BUILD.....3,850 Hours

**RETURNING TEAM......** 14 Time MATE Competition Participants

## **COMPANY INFORMATION**

Designed and manufactured by ROVOTICS
JESUIT HIGH SCHOOL ROBOTICS
Carmichael, California, USA

DISTANCE TRAVELED: 3,434 km



Team Members gather around Nautilus (See list of names and roles to the right)

### **TEAM MEMBERS**

#### Freshmen

'24 Dylan Olsen\*, Software

'24 James Randall\*, Electronics

'24 Jonah Reynolds\*, Safety Officer

'24 Adon Sharp\*, Software Sophomores

#### '23 Daniel Kriefels\*, Software

'23 Timothy Monroe, Mechanical

'23 Michael Solis, Mechanical Juniors

### <sup>1</sup>22 Charlie Diaz, CEO

'22 Nick Venegas, Electronics

'22 Taylor Vicente, COO

#### Seniors

'21 Alden Parker, Software

'21 Andrew Grindstaff, Software

<sup>'</sup>21 Luke Rosellini, Mechanical

'21 Joe Watanabe, Mechanical

#### \*New Members

Head Coach: Jay Isaacs Assistant: Steve Kiyama Cheryl Kiyama Marcus Grindstaff Michael Sharp

