

# **Octobots Specification Sheet 2025**





### **Company Info**

#### Location

Pasadena City College Pasadena, CA, United States

#### Returning Team

4th year participating in MATE ROV

#### Traveled 3540 km

### **Safety Features**

#### Custom 3D Printed Thruster Shrouds

Protects the device and user from injury

#### **Bottom-Side Kellems** Strain Relief

Prevents cable damage and electrical failures

#### Toggleable Thrust Power

Offers controlled power management & protects device from overheating

## Special Features

#### Integrated PS5 Controller

Provides for friendly-user interface

#### **Object Detection**

Inspects the condition of underwater structures

#### Translational Movement Claw Arm

Provides additional mechanical freedom

#### Adjustable Camera Angle

Enhances underwater vision

Mass

11.5 kg

## **ROV Specs**

#### **Dimensions**

Length: 66 cm Width: 46 cm Height: 37 cm

## **Build Cost**

\$4170

**Build Time** 600 hours

## **Team Members**

#### Mechanical Team

Hvacinth Ang | Year 2 Jonathan Beaton | Year 3 Devon Li |Year 1 Chansereyroth Bun | Year 2 Trina Wan | Year 1 Andrew Han | Year 1 Michael Shiu IYear 1

#### Electrical Team

Robert Barnett | Year 1 Rene Nunez | Year 4 Yukun Zhang | Year 2 Min Pyae Thway | Year 2 Faith Hockens | Year 2

#### Software Team

Adam Gonzalez | Year 2 Shin Htet Aung | Year 1 Tao Tokikawa | Year 1 Myra Interiano | Year 2

#### Advisors

**Doug Foster** Yu Chang-Chang Hou Jared Ashcroft